
Quantum Error Correction

Lecture 3



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Linear error-correcting codes

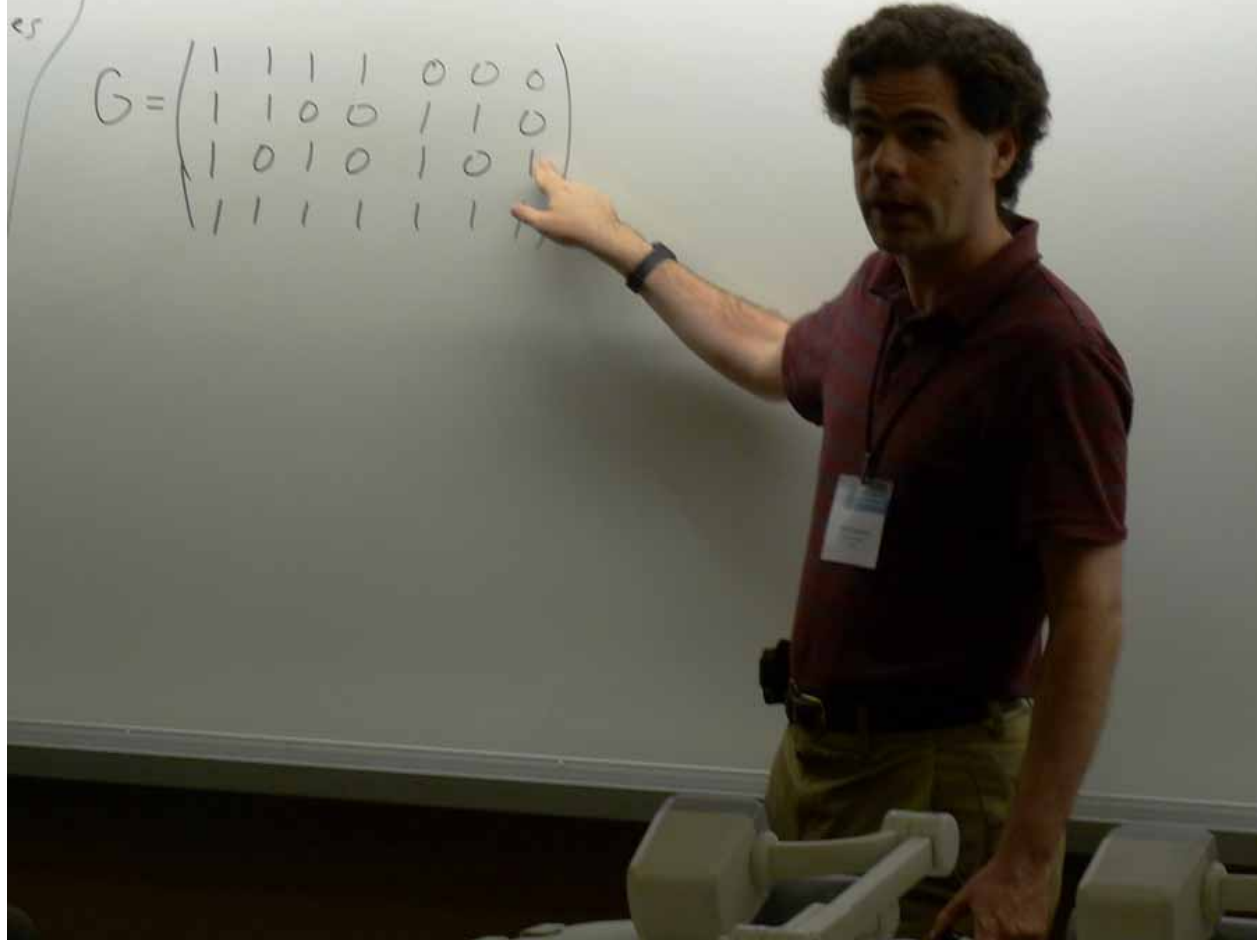
Classical code C is a set of bit strings.

Linear code: $x, y \in C \Rightarrow x \oplus y \in C$

Repetition code: $\{000, 111\}$

Generator matrix G

$$G = \begin{pmatrix} 1 & 1 & 1 & 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 0 & 1 & 0 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 \end{pmatrix}$$



codes

Generator matrix G

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Encode message $v = \begin{pmatrix} v_0 \\ v_1 \\ v_2 \\ v_3 \end{pmatrix}$

Corresponding codeword $G^T v$

$v, v' \Rightarrow v \oplus v'$ has encoding
 $G^T(v \oplus v') = G^T v \oplus G^T v'$

Parity check matrix P

$$P = \begin{pmatrix} 1 & 1 & 1 & 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 0 & 1 & 0 & 1 \end{pmatrix}$$

$x \in C$
 x a codeword $\Leftrightarrow Px = 0$

Corresponds to stabilizer

$1 \rightarrow Z, 0 \rightarrow I$

$$Z \otimes Z \otimes Z \otimes Z$$

$$Z \otimes Z \otimes I \otimes I$$

$$Z \otimes I \otimes Z \otimes I$$

$$Z \otimes I \otimes I \otimes Z$$

$$Z \otimes Z \otimes I \otimes I$$

$$Z \otimes I \otimes Z \otimes I$$

$$Z \otimes I \otimes I \otimes Z$$

Given P , we can define

$$C = \{x \mid Px = 0\}$$

$$P(x+y) = P_x + P_y = 0 + 0 = 0$$

$$PG^T = 0$$

For any linear C , define C^\perp (dual code to C) to be the code with generator matrix P & parity check matrix G .

Consider bit flip errors as a vector e . (1 in locations of errors & 0 in bits which don't have an error.)

Codeword x with error e : $x+e$

Can identify error by

$$P(x+e) = Px + Pe = Pe$$

(Error syndrome)

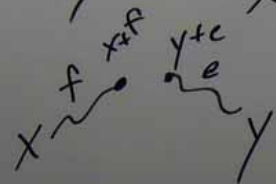
Error on i th bit: $\begin{pmatrix} 0 \\ \vdots \\ 0 \\ 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix} \Rightarrow Pe = i$ th column of P

Def.: Distance of a linear code is smallest weight of any non-zero vector in C .

Codewords x, y

Bits to flip to get from x to y :

$e = x + y$ $x + e = y$ ~~$y + e = x$~~



$f + e \neq C$

$wt(f + e) < \text{distance}$

To correct t errors, need distance $2t + 1$

$[n, k, d]$

- n physical bits
- k logical bits
- d distance

7-qubit code:

$$Z \otimes Z \otimes Z \otimes Z$$

$$Z \otimes Z \otimes$$

$$Z \otimes Z$$

$$Z \otimes$$

$$Z \otimes$$

$$Z \otimes$$

$$Z$$

$$X \otimes X \otimes X \otimes X$$

$$X \otimes X \otimes$$

$$X \otimes X$$

$$X \otimes$$

$$X \otimes$$

$$X \otimes$$

$$X$$

$$n=7$$

$$r=6$$

$$\Rightarrow k=1$$

Distance 3

$$[[7, 1, 3]]$$

CSS codes (Calderbank-Shor-Steane)

Use C_1 to correct bit flip errors, C_2 to correct phase errors.

In order to get an Abelian stabilizer, $C_2^\perp \subseteq C_1$.

$$C_1: [n, k_1, d_1], \quad C_2: [n, k_2, d_2]$$

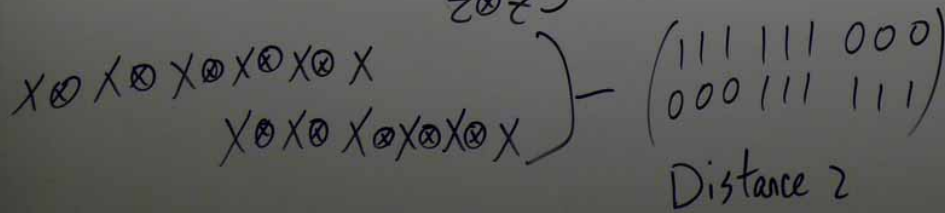
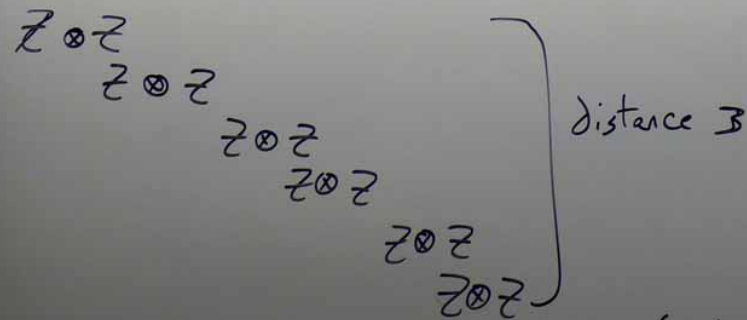
Parity check for C_1 has $n-k_1$ rows
 C_2 has $n-k_2$ rows

Stabilizer has $(n-k_1) + (n-k_2)$ generators

$$k = n - (2n - k_1 - k_2) = k_1 + k_2 - n$$

Distance of CSS code:

$$\min(d_1, d_2)$$



Stabilizer code:

Distance = min wt $N(S) \setminus S$.

Classical linear code:

Distance = min wt. nonzero vector

Degenerate quantum code

has some non-identity operator
in S with weight less than
distance.

i.e. min wt $(N(S) \setminus S)$

\neq min wt $(N(S) \setminus \{I\})$

Codewords of CSS code:

Let $x \in C_1$ } correspond to
 $\sum_{u \in C_2^\perp} |x+u\rangle$ } cosets
 C_1/C_2^\perp

($x+u \in C_1$)

Consider $y \in C_1$

with $y = x+v$, $v \in C_2^\perp$

$$\Rightarrow \sum_{u \in C_2^\perp} |x+u\rangle = \sum_{u' \in C_2^\perp} |x+v+u'\rangle$$

" " " C_2^\perp "

$$\sum_{u'' = u' + v \in C_2^\perp} |x+u''\rangle$$